

AAAI 2025

# On Effects of Steering Latent Representation for Large Language Model Unlearning

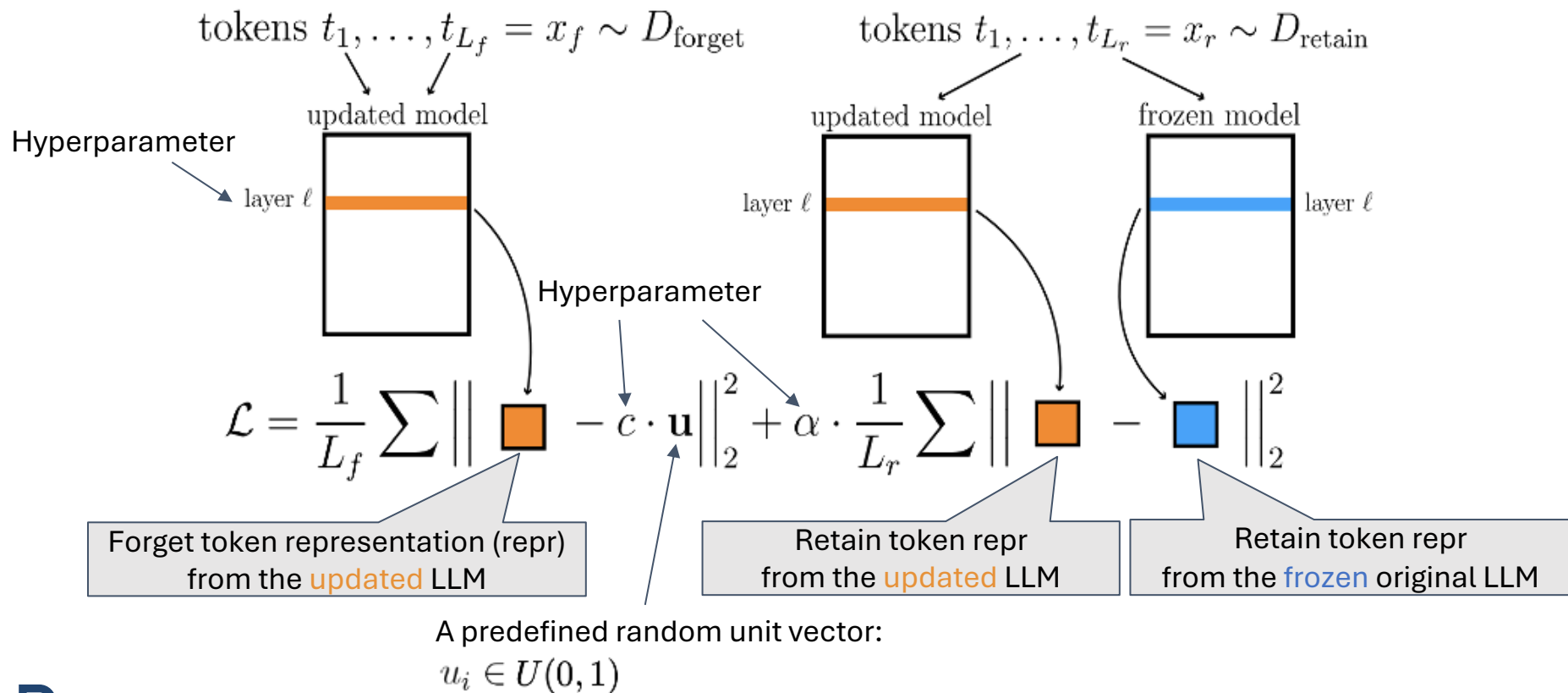
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# LLM Unlearning

- Remove or suppress specific knowledge from a pretrained LLMs, while retaining their other knowledge
- Inputs:
  - LLM parameter:  $\theta$
  - Forget set (sentences):  $D_{\text{forget}}$  (e.g., private sensitive information)
  - Retain set (sentences):  $D_{\text{retain}}$  (e.g., Wikipedia)
- Goal:
  - Update  $\theta$  so that:
  - Acc.(Questions about  $D_{\text{forget}}$ )  $\downarrow$  (e.g., What is Naoya Inoue's home address?  $\rightarrow$  ABC)
  - Acc.(Questions about  $D_{\text{retain}}$ )  $\rightarrow$  (e.g., Where is the capital of Japan?  $\rightarrow$  Tokyo)

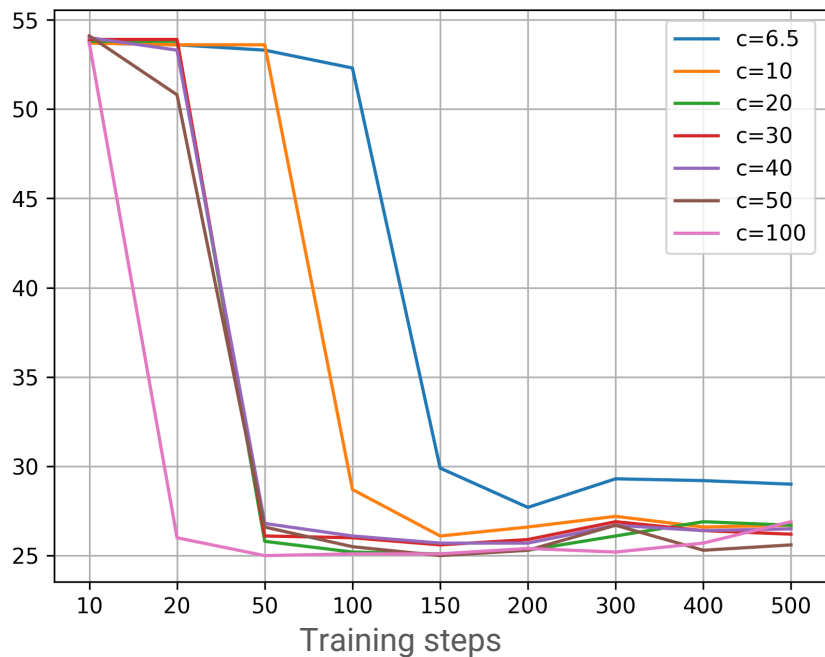
# RMU: Representation Misdirection for Unlearning



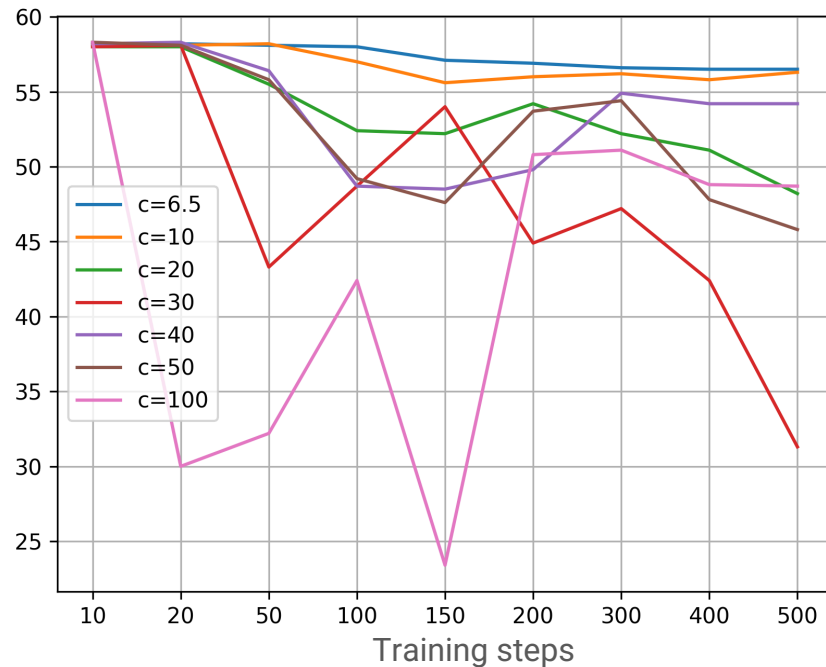
# Issues in RMU: hyperparameter tuning is hard and costly

- RMU is empirically shown to be effective for unlearning and robust against knowledge recovery attacks
- **However:** Hyperparameters  $c, l$  need careful calibration, but there is no principled way to determine  $c, l$ 
  - Needs grid search over both  $l$  and  $c$  ... but it is computationally expensive!

# Demo: $c$ needs sweetspot





QA accuracy on forget set (WMDP)



QA accuracy on retain set (MMLU)

# Our contributions

-  Theoretical and  empirical analysis of RMU:
  1. How does  $c$  affect next token prediction?
  2. What is the role and effect of  $c$ ?
  3. What is the optimal value of  $c$  for effective unlearning across layers?
  4. Why is RMU robust against knowledge recovery attacks? (see the paper)
- Propose **Adaptive RMU**, which dynamically adjusts  $c$  during unlearning
  - Higher drop-in-accuracy for forget knowledge, retaining general knowledge
  - Effective unlearning for most unlayers without additional computational overhead
  - Still needs grid search, but not over both  $l$  and  $c$ !

# Preliminaries

- **Definition 1:** Unlearned models & Logits of forget tokens

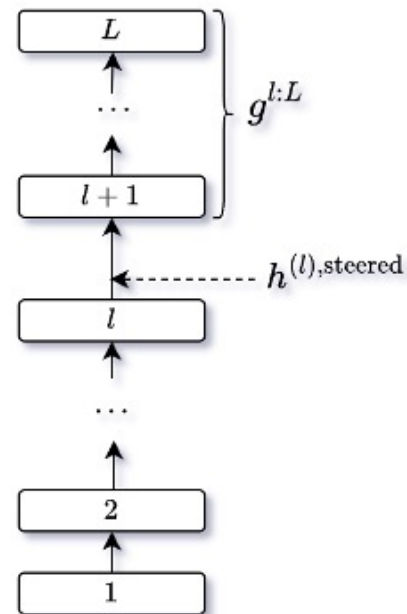
Final logits of generated forget-tokens

Unembedding matrix

$$\begin{aligned}
 f^{\text{unlearn}}(x_{F,n+1} | x_{F,1:n}) &= \mathbf{W} f^{(l:L), \text{steered}}(x_{F,n+1} | x_{F,1:n}) \\
 &= \mathbf{W} (g^{(l:L)} \circ h^{(l), \text{steered}})(x_{F,n+1} | x_{F,1:n}) \\
 &= \mathbf{W} g^{(l:L)}(h^{(l), \text{steered}}(x_{F,n+1} | x_{F,1:n})) \quad (2)
 \end{aligned}$$

Composition of transformer layers

Steered representations at layer  $l$



Transformer layers

# Preliminaries

- **Assumption 1:** A well-unlearned model pushes the representations of all forget tokens toward a predefined random vector

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$$h^{(l), \text{steered}}(x_{F,i}) = cu + \epsilon,$$

A predefined coefficient  $c$

A predefined random unit vector  $u$

Optimization Error  $\mathcal{N}(\mathbf{0}, \eta I)$   $\epsilon$



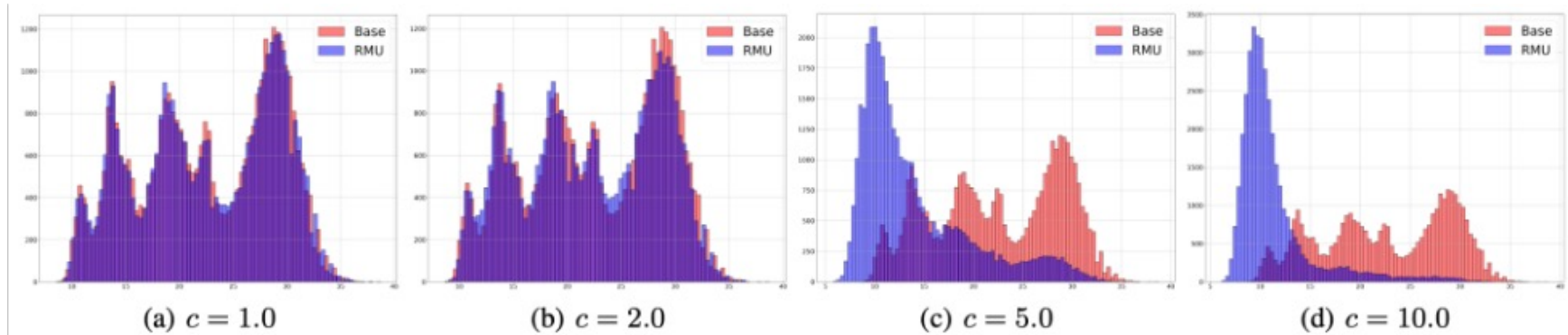
# 1) Logits are more randomized given larger $c$

**Proposition 1.** *If Assumption 1 holds, by Definition 1, the logit value of forget token  $x_{F,n+1}$  generated by unlearned model  $f^{\text{unlearn}}$  given as  $f^{\text{unlearn}}(x_{F,n+1}|x_{F,1:n})$  follows the Normal distribution  $\mathcal{N}(\mathbf{W}g^{(l:L)}(\mathbf{z}), \eta \mathbf{W} \nabla_{\mathbf{z}} g^{(l:L)}(\mathbf{z})^\top \nabla_{\mathbf{z}} g^{(l:L)}(\mathbf{z}) \mathbf{W}^\top)$ , where  $\mathbf{z} = c\mathbf{u}$ .*

Varies depending on the specific characteristics of sub-networks  $g$ , but **a larger  $c$  could introduce more randomness to the logit?**

# 1) Logits are more randomized given larger $c$

- Ask LLMs about questions related to forget set
- Distribution of answer confidence (by max logit values of ans. tokens)



- With larger  $c$ , RMU-unlearned model generates answer tokens with lower confidence  $\rightarrow$  Larger  $c$  introduces more randomness to logits

## 2) Larger $c$ aligns forget token reprs more with random vector

Jacobian matrix—a linearized  $g^{(l:k)}$  at a given input

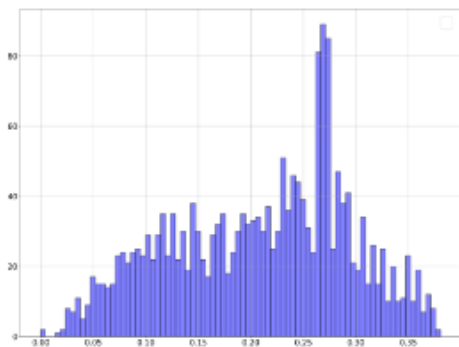
- **Proposition 2:**  $c$  and  $\cos(\mathbf{J}^{(l:k)} \mathbf{u}, \mathbf{J}^{(l:k)} (\hat{\mathbf{h}}^{(l)} - \epsilon))$  are positively correlated.

A predefined random unit vector

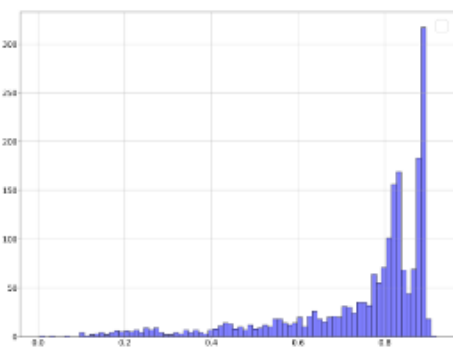
Forget token repr at layer  $l$

## 2) Larger $c$ aligns forget token reprs more with random vector

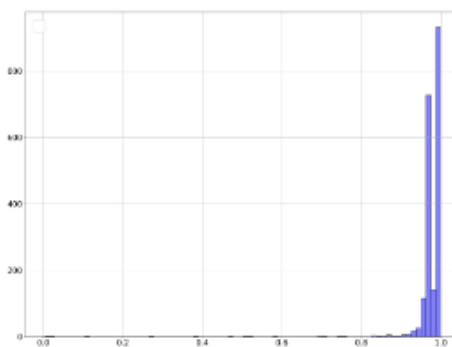
- Extract token reprs from forget set
- Compute cosine sim. between them and  $u$



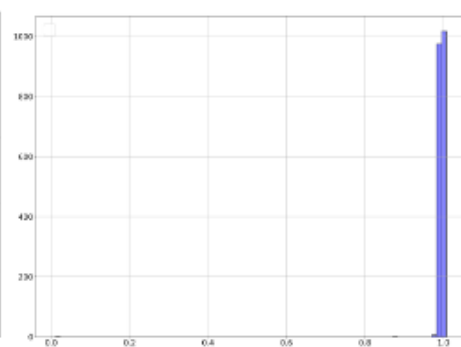
(e)  $c = 1.0$



(f)  $c = 2.0$



(g)  $c = 5.0$



(h)  $c = 10.0$

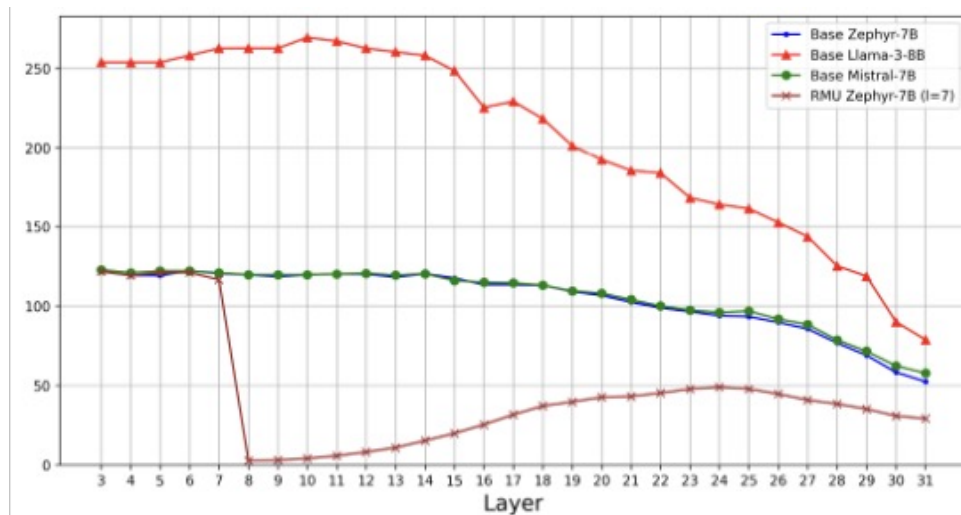
- Clearly, larger  $c$  promotes the alignment

### 3) Different layers/models require different $c$

- Define noise sensitivity of layers:

$$\Phi(g^{(l:k)}, \mathcal{D}_{\text{forget}}) = \frac{\|g^{(l:k)}(\hat{h}^{(l)}(x_F) + \xi) - g^{(l:k)}(\hat{h}^{(l)}(x_F))\|^2}{\|g^{(l:k)}(\hat{h}^{(l)}(x_F))\|^2}$$

Injected Noise



- Later layers are more robust to noise  
→ Unlearning with later layer also needs larger  $c$ ?

### 3) Different layers/models require different $c$

- Fix  $c$  ( $=6.5$ ) and unlearn with various layers  $l$
- Observe how L2 norm of each layer's repr changes



Later layers cannot be adjusted to  $c\mathbf{u}$  with smaller  $c$   
**→ Unlearn fails!**

Earlier layers can be well adjusted to  $c\mathbf{u}$

# The findings lead to AdaptiveRMU

- How does  $c$  affect next token prediction?
  - RMU tries to push all forget reprs at the intermediate layer toward a random repr
  - This randomness is propagated through layers, causing the reduction in generated token confidence
- What is the role and effect of  $c$ ?
  - Higher  $c$  leads to more randomness of the output
  - Higher  $c$  leads to more alignment between forget reprs and the random vector
- What is the optimal value of  $c$  for effective unlearning across layers?
  - Early layers require smaller noise (smaller  $c$ ) whereas later layers require larger noise (larger  $c$ ) to produce the same level of output randomness

# Proposed: Adaptive RMU (very simple yet effective)

tokens  $t_1, \dots, t_{L_f} = x_f \sim D_{\text{forget}}$       tokens  $t_1, \dots, t_{L_r} = x_r \sim D_{\text{retain}}$

updated model      updated model      frozen model

layer  $\ell$       layer  $\ell$       layer  $\ell$

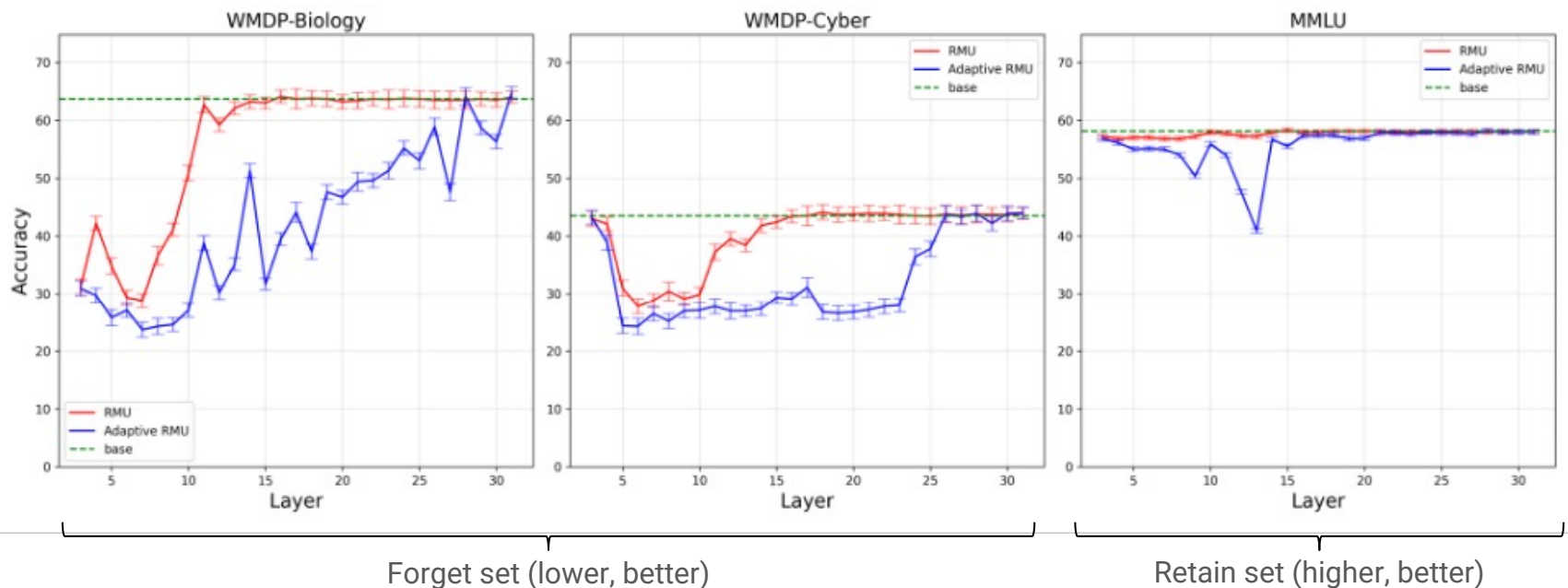
$$\mathcal{L} = \frac{1}{L_f} \sum \left\| \text{orange square} - c \cdot \mathbf{u} \right\|_2^2 + \alpha \cdot \frac{1}{L_r} \sum \left\| \text{orange square} - \text{blue square} \right\|_2^2$$

$$\mathcal{L}^{\text{adaptive}} = \frac{1}{L_f} \sum \left\| \text{orange square} - \beta \left\| \text{blue square} \right\|_2 \cdot \mathbf{u} \right\|_2^2 + \alpha \cdot \frac{1}{L_r} \sum \left\| \text{orange square} - \text{blue square} \right\|_2^2$$



# Results: AdaptiveRMU works for most layers!

- Ablation test: Fixed  $c$  (=6.5) v.s. Adaptive  $c$



# Summary

- Theoretical and empirical analysis of RMU
- Propose to use layer-adaptive  $c$ , which eliminates the need of hyperparameter tuning and even improves the unlearning performance
- Code: <https://github.com/RebelsNLU-jaist/llm-unlearning>
- Contact: Tien ([dtienuet@gmail.com](mailto:dtienuet@gmail.com)) and Naoya ([naoya-i@jaist.ac.jp](mailto:naoya-i@jaist.ac.jp))
- Lab: <https://rebelsnlu.super.site/>